Characterization of the Multicomplex Mandelbrot Set

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Introduction

Preliminaries Multicomplex Dynamics Conclusion

3D Mandelbrot Sets

3D Mandelbrot Sets

- Quaternionic Mandelbrot set: Norton, 1982
- Bicomplex Mandelbrot set (Tetrabrot): Rochon, 2000
- Spherical coordinates (Mandelbulb, Power 8): White & Nylander, 2009



(a) 3D Mandelbrot sets

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Bicomplex Numbers

Definition 1 ($\mathbb{M}(2)$ or \mathbb{BC} -space)

Let $z_1 = x_1 + x_2 \mathbf{i}_1$, $z_2 = x_3 + x_4 \mathbf{i}_1$ be two complex numbers $\mathbb{M}(1) \simeq \mathbb{C}$ with $\mathbf{i}_1^2 = -1$. A **bicomplex number** ζ is defined as:

$$\zeta = \mathbf{z}_1 + \mathbf{z}_2 \mathbf{i}_2$$

where $\mathbf{i_2^2} = -1$.

Various representations:

- In terms of four real numbers: $\zeta = x_1 + x_2\mathbf{i}_1 + x_3\mathbf{i}_2 + x_4\mathbf{j}_1$
- In terms of two idempotent elements:

$$\zeta = (z_1 - z_2 \mathbf{i}_1)\gamma_1 + (z_1 + z_2 \mathbf{i}_1)\overline{\gamma}_1$$

where $\gamma_1 = \frac{1+\mathbf{j}_1}{2}$ and $\overline{\gamma}_1 = \frac{1-\mathbf{j}_1}{2}$.

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Operations on Bicomplex Numbers

Let
$$\zeta_1 = z_1 + z_2 \mathbf{i}_2$$
 and $\zeta_2 = z_3 + z_4 \mathbf{i}_2$.

- 1) Equality: $\zeta_1 = \zeta_2 \iff z_1 = z_3$ and $z_2 = z_4$
- 2) Addition: $\zeta_1 + \zeta_2 := (z_1 + z_3) + (z_2 + z_4)\mathbf{i}_2$
- 3) Multiplication: $\zeta_1 \cdot \zeta_2 := (z_1 z_3 z_2 z_4) + (z_2 z_3 + z_1 z_4) \mathbf{i}_2$
- 4) Euclidean Norm: $|\zeta_1| = \sqrt{|z_1|^2 + |z_2|^2} = \sqrt{\sum_{i=1}^4 x_i^2}$ Remark:

• $(\mathbb{M}(2), +, \cdot)$ forms a commutative ring with unity and zero divisors.

• $(\mathbb{M}(2), +, \cdot, |\cdot|)$ forms a **Banach space**.

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Tricomplex Numbers

Definition 2 ($\mathbb{M}(3)$ or \mathbb{TC} -space)

Let $\zeta_1 = z_1 + z_2 i_2$, $\zeta_2 = z_3 + z_4 i_2$ be two bicomplex numbers. A **tricomplex number** η is defined as:

$$\eta = \zeta_1 + \zeta_2 \mathbf{i_3}$$

where $i_{3}^{2} = -1$.

Various representations:

- In terms of four complex numbers: $\eta = z_1 + z_2 \mathbf{i}_2 + z_3 \mathbf{i}_3 + z_4 \mathbf{j}_3$
- In terms of eight real numbers:

$$\eta = x_1 + x_2\mathbf{i_1} + x_3\mathbf{i_2} + x_4\mathbf{i_3} + x_5\mathbf{i_4} + x_6\mathbf{j_1} + x_7\mathbf{j_2} + x_8\mathbf{j_3}$$

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Tricomplex Numbers

Various representations (continuing):

• In terms of two idempotent elements:

$$\eta = (\zeta_1 - \zeta_2 \mathbf{i}_2)\gamma_3 + (\zeta_1 + \zeta_2 \mathbf{i}_2)\overline{\gamma}_3$$

where $\zeta_1, \zeta_2 \in \mathbb{M}(2)$, $\gamma_3 = \frac{1+j_3}{2}$ and $\overline{\gamma}_3 = \frac{1-j_3}{2}$.

• In terms of four idempotent elements:

$$\eta = \eta_{\gamma_1\gamma_3} \cdot \gamma_1\gamma_3 + \eta_{\gamma_1\overline{\gamma}_3} \cdot \gamma_1\overline{\gamma}_3 + \eta_{\overline{\gamma}_1\gamma_3} \cdot \overline{\gamma}_1\gamma_3 + \eta_{\overline{\gamma}_1\overline{\gamma}_3} \cdot \overline{\gamma}_1\overline{\gamma}_3$$

where $\eta_{\gamma_1\gamma_3}, \eta_{\gamma_1\overline{\gamma}_3}, \eta_{\overline{\gamma}_1\gamma_3}, \eta_{\overline{\gamma}_1\overline{\gamma}_3} \in \mathbb{M}(1) \simeq \mathbb{C}$ are defined as the **projections** in the plane.

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Subsets of $\mathbb{M}(3)$

Definition 3

Let $i_k\in\{i_1,i_2,i_3,i_4\}$ and $j_k\in\{j_1,j_2,j_3\},$ where $i_k^2=-1$ and $j_k^2=1.$ We define

$$\mathbb{C}(\mathbf{i_k}) := \{x_0 + x_1 \mathbf{i_k} : x_0, x_1 \in \mathbb{R}\}$$

and

$$\mathbb{D}(\mathbf{j}_{\mathbf{k}}) := \{x_0 + x_1 \mathbf{j}_{\mathbf{k}} : x_0, x_1 \in \mathbb{R}\}.$$

- C(i_k) is a subset of M(3) for k ∈ {1,2,3,4}. They are all isomorphic to C. Notice that C(i₁) = M(1).
- D(j_k) is a subset of M(3) and is isomorphic to the set of hyperbolic numbers D for k ∈ {1, 2, 3}.

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Subsets of $\mathbb{M}(3)$ (continuing)

Definition 4

Let $i_k,i_l,i_m\in\{1,i_1,i_2,i_3,i_4,j_1,j_2,j_3\}$ with $i_k\neq i_l,~i_k\neq i_m$ and $i_l\neq i_m.$ The third subset is

$$\mathbb{T}(\mathbf{i}_{\mathbf{m}},\mathbf{i}_{\mathbf{k}},\mathbf{i}_{\mathbf{l}}) := \{x_1\mathbf{i}_{\mathbf{m}} + x_2\mathbf{i}_{\mathbf{k}} + x_3\mathbf{i}_{\mathbf{l}} : x_1, x_2, x_3 \in \mathbb{R}\}.$$

- $\mathbb{T}(\mathbf{i}_{\mathbf{m}}, \mathbf{i}_{\mathbf{k}}, \mathbf{i}_{\mathbf{l}}) = \text{span}_{\mathbb{R}}\{\mathbf{i}_{\mathbf{m}}, \mathbf{i}_{\mathbf{k}}, \mathbf{i}_{\mathbf{l}}\}.$
- This sub-vector space of M(3) is used to make 3D slices in the tricomplex Mandelbrot set.

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Multicomplex Numbers

More generally, the **multicomplex numbers** of order n (also called *n*-complex numbers) are obtained by using the previous duplication process recursively. They were first described by the Italian mathematician Corrado Segre in 1892. Indeed, for any integer $n \ge 1$, the set of multicomplex numbers of order n is defined as

$$\mathbb{M}(n) := \{\eta_1 + \eta_2 \mathbf{i_n} : \eta_1, \eta_2 \in \mathbb{M}(n-1)\}$$

with $i_n^2=-1$ and $\mathbb{M}(0):=\mathbb{R}.$ Moreover, multicomplex addition and multiplication are defined similarly to the analogous complex operations, meaning that

$$(\eta_1 + \eta_2 \mathbf{i}_{\mathbf{n}}) + (\zeta_1 + \zeta_2 \mathbf{i}_{\mathbf{n}}) = (\eta_1 + \zeta_1) + (\eta_2 + \zeta_2) \mathbf{i}_{\mathbf{n}};$$

$$(\eta_1 + \eta_2 \mathbf{i}_{\mathbf{n}})(\zeta_1 + \zeta_2 \mathbf{i}_{\mathbf{n}}) = (\eta_1 \zeta_1 - \eta_2 \zeta_2) + (\eta_1 \zeta_2 + \eta_2 \zeta_1) \mathbf{i}_{\mathbf{n}}.$$

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The Mandelbrot Set

Definition 5

Let $Q_c(z) = z^2 + c$ a quadratic complex polynomial. The so-called Mandelbrot set is defined as follows:

 $\mathcal{M}^2 = \{ c \in \mathbb{C} : \{ Q_c^m(0) \}_{m=1}^{\infty} \text{ is bounded } \}.$



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Tricomplex Mandelbrot Set: The Metatronbrot

Definition 6

Let $Q_c(\eta) = \eta^2 + c$ where $\eta, c \in \mathbb{M}(3)$. The tricomplex Mandelbrot set (also called *Metatronbrot*) is define as the set

 $\mathcal{M}_3^2 := \left\{ c \in \mathbb{M}(3) \, : \, \left\{ \mathit{Q}_c^m(0)
ight\}_{m=1}^\infty \, \, \text{is bounded} \,
ight\}.$

Theorem 7

A tricomplex number c is in \mathcal{M}_3^2 if and only if $|Q_c^m(0)| \le 2$ for all natural number $m \ge 1$.

NOTE: The name Metatronbrot refers to the so-called Metatron's cube of the Flower of Life.

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Principal 3D slices of \mathcal{M}_3^2

To visualize the 8D tricomplex Mandelbrot set, we have to define a principal 3D slice of $\mathcal{M}_3^2.$

$$\mathcal{T}^2 := \mathcal{T}^2(\mathbf{i}_{\mathsf{m}}, \mathbf{i}_{\mathsf{k}}, \mathbf{i}_{\mathsf{l}}) = \{ c \in \mathbb{T}(\mathbf{i}_{\mathsf{m}}, \mathbf{i}_{\mathsf{k}}, \mathbf{i}_{\mathsf{l}}) \ : \ \{Q_c^m(0)\}_{m=1}^{\infty} \text{ is bounded } \} \,.$$

- There are 56 possible principal 3D slices.
- $\mathcal{T}^2(\mathbf{i}_m, \mathbf{i}_k, \mathbf{i}_l) = \mathcal{M}_3^2 \cap \mathbb{T}(\mathbf{i}_m, \mathbf{i}_k, \mathbf{i}_l).$
- The concept of **idempotent 3D slices** can be also defined using the idempotent basis.

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Equivalence between principal 3D slices of \mathcal{M}_3^2

Definition 8

Let $\mathcal{T}_1^2(\mathbf{i_m}, \mathbf{i_k}, \mathbf{i_l})$ and $\mathcal{T}_2^2(\mathbf{i_n}, \mathbf{i_q}, \mathbf{i_s})$ be two principal 3D slices of the tricomplex Mandelbrot set \mathcal{M}_3^2 . Then, $\mathcal{T}_1^2 \sim \mathcal{T}_2^2$ if we have a bijective linear mapping $\varphi : \mathcal{M}_1 \to \mathcal{M}_2$ such that $\varphi(\mathbb{T}_1(\mathbf{i_m}, \mathbf{i_k}, \mathbf{i_l})) = \mathbb{T}_2(\mathbf{i_n}, \mathbf{i_q}, \mathbf{i_s})$ and, for all $c \in \mathbb{T}_1(\mathbf{i_m}, \mathbf{i_k}, \mathbf{i_l})$

$$(\varphi \circ Q_c \circ \varphi^{-1})(\eta) = Q_{\varphi(c)}(\eta) \ \forall \eta \in M_2,$$

where M_i is the smallest sub-vector space of $\mathbb{M}(3)$ containing all iterates of $Q_{c_i}^m(0)$ with $c_i \in \mathbb{T}_i$ for i = 1, 2. In that case, we say that \mathcal{T}_1^2 and \mathcal{T}_2^2 have the **same dynamics**.

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Principal Slices of \mathcal{M}_3^2

The number of principal 3D slices of the Metatronbrot \mathcal{M}_3^2 can be reduced to eight slices.

Theorem 9

There are eight **principal 3D slices** of the tricomplex Mandelbrot set \mathcal{M}_3^2 :

- $\mathcal{T}^2(1, i_1, i_2)$ called Tetrabrot;
- $\mathcal{T}^2(i_1,j_1,j_2)$ called Hourglassbrot;
- $\mathcal{T}^2(1, j_1, j_2)$ called Airbrot;
- $\mathcal{T}^2(i_1, i_2, i_3)$ called Metabrot;
- $\mathcal{T}^2(j_1, j_2, j_3)$ called Firebrot;
- $\mathcal{T}^2(i_1,i_2,j_1)$ called Mousebrot;
- $\mathcal{T}^2(i_1,i_2,j_2)$ called Turtlebrot;
- $\mathcal{T}^2(1, i_1, j_1)$ called Arrowheadbrot.

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Family Shooting of the Metatronbrot: $\eta^2 + c$



- (a) Tetrabrot
- (b) Hourglassbrot

(c) Airbrot





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Multicomplex Mandelbrot Set

We now consider the multicomplex case. Let $Q_{p,c}(\eta) = \eta^p + c$ and denote

$$Q_{p,c}^{m}(\eta) = \underbrace{(Q_{p,c} \circ Q_{p,c} \circ \cdots \circ Q_{p,c})}_{m \text{ times}}(\eta).$$

Using the function $Q_{p,c}$, we already defined the standard Mandelbrot set as

$$\mathcal{M}^2=ig\{c\in\mathbb{M}(1)\ :\ \{Q^m_{2,c}(0)\}_{m=1}^\infty ext{ is bounded }ig\}.$$

We can easily modify this last definition to obtain the following more general one.

Definition 10

Let $n, p \in \mathbb{N}$ such that $p \ge 2$. The *n*-complex **Multibrot** set of order *p* is defined as

$$\mathcal{M}^p_n = \big\{ c \in \mathbb{M}(n) \ : \ \{Q^m_{p,c}(0)\}_{m=1}^\infty \text{ is bounded } \big\}.$$

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Characterization the 3D Slices

In the same way, we can generalized the previous concept of principal 3D slices into the multicomplexe spaces. In that case we obtain $\binom{2^n}{3}$ possible 3D slices. The next result gives a characterization of those slices.

Theorem 11

Let \mathcal{T}_1^p be a principal 3D slice of \mathcal{M}_n^p . There always exists a tricomplex principal 3D slice \mathcal{T}_2^p such that $\mathcal{T}_1^p \sim \mathcal{T}_2^p$ up to an affine transformation.

In other words, in that context, it is not necessary to explore principal 3D slices beyond the tricomplex space. Hence, the tricomplex space is, in a way, optimal.

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Conclusion

In future works, it will therefore be possible to look into Multibrot principal slices specifically in the tricomplex case. In the specific case of the Metatronbrot \mathcal{M}_3^2 , we know already that there are only eight principal 3D slices: the Tetrabrot, the Arrowheadbrot, the Hourglassbrot, the Airbrot, the Firebrot, the Mousebrot, the Metabrot and the Turtlebrot. Hence, for p = 2, these are the only principal 3D slices of the Mandelbrot set generalized to the multicomplex spaces.

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Reference

Thanks for your attention!



(a) Hybridization between the Tetrabrot and a 3D kleinian IFS

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Characterization of the Multicomplex Mandelbrot Set

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References

Table of imaginary units

•	1	i_1	i ₂	i ₃	i4	\mathbf{j}_1	j 2	j 3
1	1	i_1	i ₂	i ₃	i4	j 1	j ₂	j ₃
i_1	i_1	-1	j 1	j 2	— j 3	$-i_2$	$-i_3$	i4
i 2	i ₂	j 1	-1	j 3	— j 2	$-i_1$	i4	$-i_3$
i3	i3	j 2	j 3	- 1	$-\mathbf{j}_1$	i4	$-i_1$	$-i_2$
i4	i4	— j 3	$-\mathbf{j}_2$	$-\mathbf{j}_1$	-1	i ₃	i2	i_1
j 1	j 1	$-i_2$	$-i_1$	i 4	i ₃	1	− j ₃	$-\mathbf{j}_2$
j ₂	j2	$-i_3$	i4	$-i_1$	i 2	— j 3	1	$-\mathbf{j}_1$
j ₃	j3	i4	$-i_3$	$-i_2$	i_1	— j 2	$-\mathbf{j}_1$	1

Table: Product of tricomplex imaginary units

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